#### **General Description**

The MAX4450 single and MAX4451 dual op amps are unity-gain-stable devices that combine high-speed performance with Rail-to-Rail® outputs. Both devices operate from a +4.5V to +11V single supply or from ±2.25V to ±5.5V dual supplies. The common-mode input voltage range extends beyond the negative power-supply rail (ground in single-supply applications).

The MAX4450/MAX4451 require only 6.5mA of guiescent supply current per op amp while achieving a 210MHz -3dB bandwidth and a 485V/µs slew rate. Both devices are an excellent solution in low-power/lowvoltage systems that require wide bandwidth, such as video, communications, and instrumentation.

The MAX4450 is available in the ultra-small 5-pin SC70 package, while the MAX4451 is available in a spacesaving 8-pin SOT23.

Set-Top Boxes

Video Line Driver

**Digital Cameras** 

**CCD** Imaging Systems

Surveillance Video Systems **Battery-Powered Instruments** 

Analog-to-Digital Converter Interface

Video Routing and Switching Systems

#### **Applications**

#### **Features**

- Ultra-Small SC70-5, SOT23-5, and SOT23-8 **Packages**
- Low Cost
- High Speed 210MHz -3dB Bandwidth 55MHz 0.1dB Gain Flatness 485V/us Slew Rate
- Single +4.5V to +11V Operation
- Rail-to-Rail Outputs
- Input Common-Mode Range Extends Beyond VEE
- Low Differential Gain/Phase: 0.02%/0.08°
- Low Distortion at 5MHz -65dBc SFDR -63dB Total Harmonic Distortion

### **Ordering Information**

PART	TEMP. RANGE	PIN- PACKAGE	TOP MARK		
MAX4450EXK-T	-40°C to +85°C	5 SC70-5	AAA		
MAX4450EUK-T	-40°C to +85°C	5 SOT23-5	ADKP		
MAX4451EKA-T	-40°C to +85°C	8 SOT23-8	AAAA		
MAX4451ESA	-40°C to +85°C	8 SO	—		

#### Rf 240 $R_{TO}$ 50 $\Omega$ νοιιτ MAXIN $Z_0 = 50\Omega$ 1AX4451 R<sub>0</sub> $50\Omega$ RTIN 500 UNITY-GAIN LINE DRIVER $(R_L = R_O + R_{TO})$

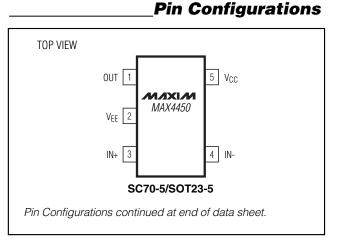
Rail-to-Rail is a registered trademark of Nippon Motorola, Ltd.

#### **MIXI/M**

Maxim Integrated Products 1

For free samples and the latest literature, visit www.maxim-ic.com or phone 1-800-998-8800. For small orders, phone 1-800-835-8769.

#### Typical Operating Circuit



#### **ABSOLUTE MAXIMUM RATINGS**

Supply Voltage (V<sub>CC</sub> to V<sub>EE</sub>).....+12V IN\_-, IN\_+, OUT\_.....(V<sub>EE</sub> - 0.3V) to (V<sub>CC</sub> + 0.3V) Output Short-Circuit Current to V<sub>CC</sub> or V<sub>EE</sub>..........150mA Continuous Power Dissipation (T<sub>A</sub> = +70°C) 5-Pin SC70-5 (derate 2.5mW/°C above +70°C).......200mW 5-Pin SOT23-5 (derate 7.1mW/°C above +70°C).......571mW

8-Pin SOT23-8 (derate 5.26mW/°C above +7	′0°C)421mW
8-Pin SO (derate 5.9mW/°C above +70°C)	471mW
Operating Temperature Range	
Storage Temperature Range	
Lead Temperature (soldering, 10s)	+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or at any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### DC ELECTRICAL CHARACTERISTICS

(V<sub>CC</sub> = +5V, V<sub>EE</sub> = 0, R<sub>L</sub> =  $\infty$  to V<sub>CC</sub>/2, V<sub>OUT</sub> = V<sub>CC</sub>/2, T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted. Typical values are at T<sub>A</sub> = +25°C.) (Note 1)

PARAMETER	SYMBOL	C	MIN	ТҮР	MAX	UNITS		
Input Common-Mode Voltage Range	V <sub>CM</sub>	Guaranteed by CN	V <sub>EE</sub> - 0.20		V <sub>CC</sub> 2.25	V		
Input Offset Voltage (Note 2)	Vos				4	26	mV	
Input Offset Voltage Matching					1.0		mV	
Input Offset Voltage Temperature Coefficient	TCvos				8		µV/°C	
Input Bias Current	IB	(Note 2)			6.5	20	μA	
Input Offset Current	los	(Note 2)			0.5	4	μA	
Input Resistance	RIN	Differential mode	$(-1V \le V_{IN} \le +1V)$		70		kΩ	
Input nesistance	אוח	Common mode (-0	$0.2V \le V_{CM} \le +2.75V$ )		3		MΩ	
Common-Mode Rejection Ratio	CMRR	$(V_{EE} - 0.2V) \le V_{CN}$	1≤(V <sub>CC</sub> - 2.25V)	70	95		dB	
		$0.25V \le V_{OUT} \le 4.$	50	60				
Open-Loop Gain (Note 2)	Avol	$0.5V \le V_{OUT} \le 4.5$	48	58		dB		
		$1V \le V_{OUT} \le 4V, R$		57				
	Vout	$R_L = 2k\Omega$	V <sub>CC</sub> - V <sub>OH</sub>		0.05	0.20		
			V <sub>OL</sub> - V <sub>EE</sub>		0.05	0.15	- - - - - V	
		$R_L = 150\Omega$	Vcc - Voн		0.30	0.50		
Output Voltage Swing (Note 2)			V <sub>OL</sub> - V <sub>EE</sub>		0.25	0.80		
		$R_L = 75\Omega$	V <sub>CC</sub> - V <sub>OH</sub>		0.5	0.80		
			VOL - VEE		0.5	1.75		
	IOUT	D 500	Sourcing	45	70		— mA	
Output Current		$R_L = 50\Omega$	Sinking	25	50			
Output Short-Circuit Current	Isc	Sinking or sourcing			±120		mA	
Open-Loop Output Resistance	ROUT				8		Ω	
Power-Supply Rejection Ratio (Note 3)			$V_{EE} = 0, V_{CM} = 2V$	46	62		aD	
		$V_{CC} = 5V$	54	69		- dB		
Operating Supply-Voltage Range	Vs	VCC to VEE		4.5		11.0	V	
Quiescent Supply Current (per amplifier)	IS				6.5	9.0	mA	

#### AC ELECTRICAL CHARACTERISTICS

(V<sub>CC</sub> = +5V, V<sub>EE</sub> = 0, V<sub>CM</sub> = +2.5V, R<sub>F</sub> = 24 $\Omega$ , R<sub>L</sub> = 100 $\Omega$  to V<sub>CC</sub>/2, V<sub>OUT</sub> = V<sub>CC</sub>/2, A<sub>VCL</sub> = +1V/V, T<sub>A</sub> = +25°C, unless otherwise noted.)

PARAMETER	SYMBOL	CONE	MIN	ТҮР	MAX	UNITS		
Small-Signal -3dB Bandwidth	BWSS	V <sub>OUT</sub> = 100mVp-p	210			MHz		
Large-Signal -3dB Bandwidth	BWLS	V <sub>OUT</sub> = 2Vp-p	175			MHz		
Bandwidth for 0.1dB Gain Flatness	BW <sub>0.1dB</sub>	V <sub>OUT</sub> = 100mVp-p	55			MHz		
Slew Rate	SR	V <sub>OUT</sub> = 2V step		485			V/µs	
Settling Time to 0.1%	ts	Vout = 2V step			16			
Rise/Fall Time	t <sub>R</sub> , t <sub>F</sub>	V <sub>OUT</sub> = 100mVp-p			4		ns	
Spurious-Free Dynamic Range	SFDR	$f_{\rm C} = 5 {\rm MHz}, {\rm V}_{\rm OUT} = 2 {\rm V}$	-65			dBc		
	HD	fc = 5MHz, V <sub>OUT</sub> = 2Vp-p	2nd harmonic		-65			
Harmonic Distortion			3rd harmonic		-58		aDa	
			Total harmonic distortion		-63		dBc	
Two-Tone, Third-Order Intermodulation Distortion	IP3	f1 = 4.7MHz, f2 = 4.8MHz, V <sub>OUT</sub> = 1Vp-p			66		dBc	
Channel-to-Channel Isolation	CHISO	Specified at DC			102		dB	
Input 1dB Compression Point		$f_{C} = 10MHz, A_{VCL} = +$		14		dBm		
Differential Phase Error	DP	NTSC, $R_L = 150\Omega$		0.08		degrees		
Differential Gain Error	DG	NTSC, $R_L = 150\Omega$	0.02		%			
Input Noise-Voltage Density	en	f = 10kHz 10			nV/√Hz			
Input Noise-Current Density	in	f = 10kHz 1.8			pA/√Hz			
Input Capacitance	CIN			1		pF		
Output Impedance	Zout	f = 10MHz		1.5		Ω		

**Note 1:** All devices are 100% production tested at  $T_A = +25$ °C. Specifications over temperature limits are guaranteed by design. **Note 2:** Tested with V<sub>CM</sub> = +2.5V.

Note 3: PSR for single +5V supply tested with  $V_{EE} = 0$ ,  $V_{CC} = +4.5V$  to +5.5V; PSR for dual ±5V supply tested with  $V_{EE} = -4.5V$  to -5.5V,  $V_{CC} = +4.5V$  to +5.5V.

 $(V_{CC} = +5V, V_{EE} = 0, V_{CM} = +2.5V, A_{VCL} = +1V/V, R_F = 24\Omega, R_L = 100\Omega$  to  $V_{CC}/2, T_A = +25^{\circ}C$ , unless otherwise noted.)

**Typical Operating Characteristics** 

VOLTAGE SWING (Vp-p)

MIXIM

#### **SMALL-SIGNAL GAIN vs. FREQUENCY** LARGE-SIGNAL GAIN vs. FREQUENCY **GAIN FLATNESS vs. FREQUENCY** 0.4 4 4 $V_{OUT} = 100 \text{mVp-p}$ $V_{OUT} = 100 \text{mVp-p}$ 0.3 3 $V_{OUT} = 2Vp-p$ 3 2 0.2 2 0.1 1 1 0 0 GAIN (dB) 0 (dB) GAIN (dB) GAIN (( -1 -0.1 -1 -0.2 -2 -2 -0.3 -3 -3 -0.4 -4 -4 -5 -5 -0.5 -6 -0.6 -6 100k 10M 100k 1M 10M 100M 1G 100k 1M 100M 1G 1M 10M 100M 1G FREQUENCY (Hz) FREQUENCY (Hz) FREQUENCY (Hz) **OUTPUT IMPEDANCE vs. FREQUENCY DISTORTION vs. FREQUENCY DISTORTION vs. FREQUENCY** 0 0 100 $V_{OUT} = 2Vp-p$ -10 V<sub>OUT</sub> = 2Vp-p -10 $A_{VCL} = +2V/V$ $A_{VCL} = +1V/V$ -20 -20 10 -30 -30 IMPEDANCE ( $\Omega$ ) DISTORTION (dBc) DISTORTION (dBc -40 -40 2ND HARMONIC 1 -50 -50 2ND HARMONIC -60 -60 -70 -70 0.1 3RD HARMONIC -80 3BD HARMONIC -80 | | | | |||| -90 -90 -100 0.01 -100 100k 1M 10M 100M 100k 100M 100k 10M 100M 1G 1M 10M 1M FREQUENCY (Hz) FREQUENCY (Hz) FREQUENCY (Hz) **DISTORTION vs. VOLTAGE SWING DISTORTION vs. FREQUENCY DISTORTION vs. RESISTIVE LOAD** 0 0 0 11111 $f_0 = 5MHz$ V<sub>OUT</sub> = 2Vp-p -10 $f_0 = 5 MHz$ -10 -10 $A_{VCL} = +1V/V$ $A_{VCL} = +5V/V$ V<sub>OUT</sub> = 2Vp-p -20 -20 -20 $A_{VCL} = +1V/V$ -30 -30 -30 DISTORTION (dBc) **DISTORTION** (dBc) **DISTORTION (dBc** -40 -40 -40 2ND HARMONIC -50 -50 -50 **3RD HARMONIC** -60 -60 -60 3RD HARMONIC 2ND HARMONIC -70 -70 -70 2ND HARMONIC -80 -80 -80 **3RD HARMONIC** -90 -90 -90 -100 -100 -100 100k 1M 10M 100M 0 200 400 600 800 1000 1200 0.5 1.0 1.5 2.0

 $R_{LOAD}(\Omega)$ 

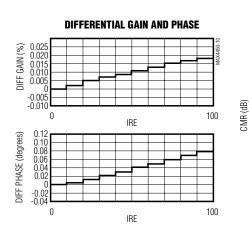
MAX4450/MAX4451

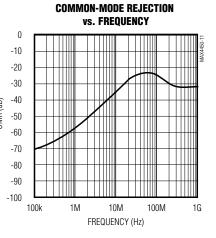
4

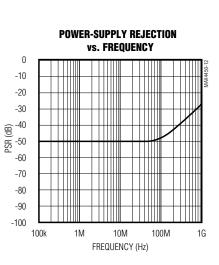
FREQUENCY (Hz)

#### **Typical Operating Characteristics (continued)**

 $(V_{CC} = +5V, V_{EE} = 0, V_{CM} = +2.5V, A_{VCL} = +1V/V, R_F = 24\Omega, R_L = 100\Omega$  to  $V_{CC}/2, T_A = +25^{\circ}C$ , unless otherwise noted.)



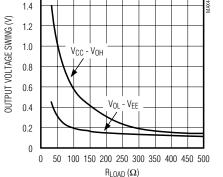




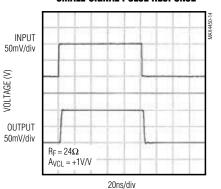
MAX4450/MAX4451

OUTPUT VOLTAGE SWING vs. RESISTIVE LOAD

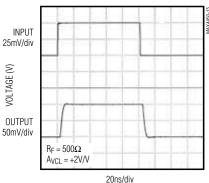
1.6

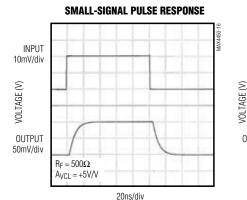


SMALL-SIGNAL PULSE RESPONSE

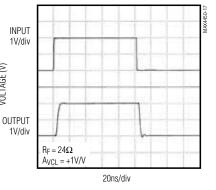


SMALL-SIGNAL PULSE RESPONSE

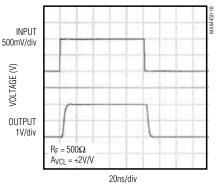




LARGE-SIGNAL PULSE RESPONSE



#### LARGE-SIGNAL PULSE RESPONSE



#### **Typical Operating Characteristics (continued)**

 $(V_{CC} = +5V, V_{EE} = 0, V_{CM} = +2.5V, A_{VCL} = +1V/V, R_F = 24\Omega, R_L = 100\Omega$  to  $V_{CC}/2, T_A = +25^{\circ}C$ , unless otherwise noted.) LARGE-SIGNAL PULSE RESPONSE **CURRENT NOISE vs. FREQUENCY VOLTAGE NOISE vs. FREQUENCY** 100 100 INPUT 1V/div /OLTAGE NOISE (pA/√Hz) CURRENT NOISE (pA/VHz) VOLTAGE (V) 10 10 INPUT 1V/div  $R_F = 500\Omega$  $A_{VCL} = +2V/V$ 

FREQUENCY (Hz)

1 10 100 1k 10k 100k 1M 10M

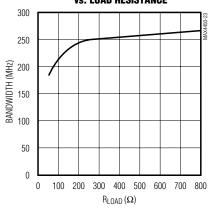
**ISOLATION RESISTANCE** vs. CAPACITIVE LOAD 16 15 14 SMALL SIGNAL 13  $(V_{OUT} = 100 \text{mVp-p})$ 12 11 10 LARGE SIGNAL (V<sub>OUT</sub> = 2Vp-p) 9 50 100 150 200 250 300 350 400 450 500 0 CLOAD (pF)

**SMALL-SIGNAL BANDWIDTH** vs. LOAD RESISTANCE

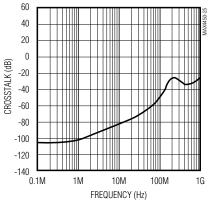
10 100 1k 10k 100k

1

1

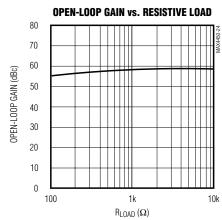


MAX4451 **CROSSTALK vs. FREQUENCY** 





20ns/div



MIXIM

1M

FREQUENCY (Hz)

10M

PIN		NAME	FUNCTION				
MAX4450	MAX4451		FUNCTION				
1	_	OUT	Amplifier Output				
2	4	VEE	Negative Power Supply or Ground (in single- supply operation)				
3		IN+	Noninverting Input				
4	_	IN-	Inverting Input				
5	8	Vcc	Positive Power Supply				
_	1	OUTA	Amplifier A Output				
	2	INA-	Amplifier A Inverting Input				
	3	INA+	Amplifier A Noninverting Input				
_	7	OUTB	Amplifier B Output				
_	6	INB-	Amplifier B Inverting Input				
_	5	INB+	Amplifier B Noninverting Input				

#### Pin Description

#### Inverting and Noninverting Configurations

Select the gain-setting feedback (RF) and input (RG) resistor values to fit your application. Large resistor values increase voltage noise and interact with the amplifier's input and PC board capacitance. This can generate undesirable poles and zeros and decrease bandwidth or cause oscillations. For example, a noninverting gain-of-two configuration ( $R_F = R_G$ ) using  $1k\Omega$ resistors, combined with 1pF of amplifier input capacitance and 1pF of PC board capacitance, causes a pole at 159MHz. Since this pole is within the amplifier bandwidth, it jeopardizes stability. Reducing the  $1k\Omega$  resistors to  $100\Omega$  extends the pole frequency to 1.59GHz, but could limit output swing by adding  $200\Omega$  in parallel with the amplifier's load resistor. Table 1 lists suggested feedback and gain resistors, and bandwidths for several gain values in the configurations shown in Figures 1a and 1b.

**Layout and Power-Supply Bypassing** These amplifiers operate from a single +4.5V to +11Vpower supply or from dual  $\pm 2.25V$  to  $\pm 5.5V$  supplies. For single-supply operation, bypass V<sub>CC</sub> to ground with a

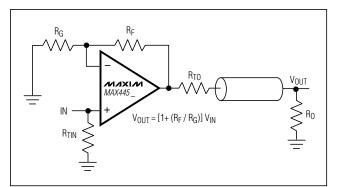


Figure 1a. Noninverting Gain Configuration

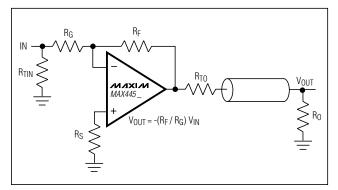


Figure 1b. Inverting Gain Configuration

#### **Detailed Description**

The MAX4450/MAX4451 are single-supply, rail-to-rail, voltage-feedback amplifiers that employ current-feedback techniques to achieve 485V/µs slew rates and 210MHz bandwidths. Excellent harmonic distortion and differential gain/phase performance make these amplifiers an ideal choice for a wide variety of video and RF signal-processing applications.

The output voltage swings to within 55mV of each supply rail. Local feedback around the output stage ensures low open-loop output impedance to reduce gain sensitivity to load variations. The input stage permits common-mode voltages beyond the negative supply and to within 2.25V of the positive supply rail.

#### Applications Information

#### **Choosing Resistor Values**

#### Unity-Gain Configuration

The MAX4450/MAX4451 are internally compensated for unity gain. When configured for unity gain, the devices require a 24 $\Omega$  resistor (R<sub>F</sub>) in series with the feedback path. This resistor improves AC response by reducing the Q of the parallel LC circuit formed by the parasitic feedback capacitance and inductance.



MAX4450/MAX4451

COMPONENT	GAIN (V/V)									
	+1	-1	+2	-2	+5	-5	+10	-10	+25	-25
$R_{F}\left(\Omega ight)$	24	500	500	500	500	500	500	500	500	1200
R <sub>G</sub> (Ω)	∞	500	500	250	124	100	56	50	20	50
$R_{S}\left(\Omega\right)$	—	0	—	0		0		0	_	0
R <sub>TIN</sub> (Ω)	49.9	56	49.9	62	49.9	100	49.9	∞	49.9	∞
R <sub>TO</sub> (Ω)	49.9	49.9	49.9	49.9	49.9	49.9	49.9	49.9	49.9	49.9
Small-Signal -3dB Bandwidth (MHz)	210	100	95	50	25	25	11	15	5	10

#### **Table 1. Recommended Component Values**

**Note:**  $R_L = R_O + R_{TO}$ ;  $R_{TIN}$  and  $R_{TO}$  are calculated for 50 $\Omega$  applications. For 75 $\Omega$  systems,  $R_{TO} = 75\Omega$ ; calculate  $R_{TIN}$  from the following equation:  $R_{TIN} = \frac{75}{\Omega}$ 

$$R_{\text{TIN}} = \frac{75}{1 - \frac{75}{R_{\text{G}}}}$$

 $0.1\mu F$  capacitor as close to the pin as possible. If operating with dual supplies, bypass each supply with a  $0.1\mu F$  capacitor.

Maxim recommends using microstrip and stripline techniques to obtain full bandwidth. To ensure that the PC board does not degrade the amplifier's performance, design it for a frequency greater than 1GHz. Pay careful attention to inputs and outputs to avoid large parasitic capacitance. Whether or not you use a constantimpedance board, observe the following design guidelines:

- Don't use wire-wrap boards; they are too inductive.
- Don't use IC sockets; they increase parasitic capacitance and inductance.
- Use surface-mount instead of through-hole components for better high-frequency performance.
- Use a PC board with at least two layers; it should be as free from voids as possible.
- Keep signal lines as short and as straight as possible. Do not make 90° turns; round all corners.

#### Rail-to-Rail Outputs, Ground-Sensing Input

The input common-mode range extends from (V<sub>EE</sub> - 200mV) to (V<sub>CC</sub> - 2.25V) with excellent commonmode rejection. Beyond this range, the amplifier output is a nonlinear function of the input, but does not undergo phase reversal or latchup.

The output swings to within 55mV of either power-supply rail with a  $2k\Omega$  load. The input ground sensing

and the rail-to-rail output substantially increase the dynamic range. With a symmetric input in a single +5V application, the input can swing 2.95Vp-p and the output can swing 4.9Vp-p with minimal distortion.

#### **Output Capacitive Loading and Stability**

The MAX4450/MAX4451 are optimized for AC performance. They are not designed to drive highly reactive loads, which decrease phase margin and may produce excessive ringing and oscillation. Figure 2 shows a circuit that eliminates this problem. Figure 3 is a graph of the optimal isolation resistor (Rs) vs. capacitive load. Figure 4 shows how a capacitive load causes excessive peaking of the amplifier's frequency response if the capacitor is not isolated from the amplifier by a resistor. A small isolation resistor (usually  $20\Omega$  to  $30\Omega$ ) placed before the reactive loads, AC performance is controlled by the interaction of the load capacitance and the isolation resistor. Figure 5 shows the effect of a  $27\Omega$  isolation resistor on closed-loop response.

Coaxial cable and other transmission lines are easily driven when properly terminated at both ends with their characteristic impedance. Driving back-terminated transmission lines essentially eliminates the line's capacitance.

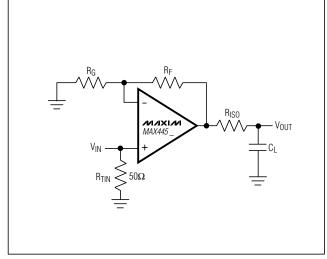


Figure 2. Driving a Capacitive Load Through an Isolation Resistor

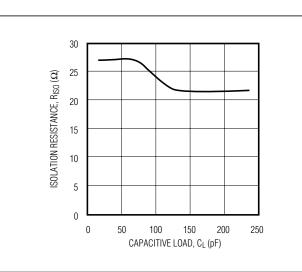


Figure 3. Capacitive Load vs. Isolation Resistance

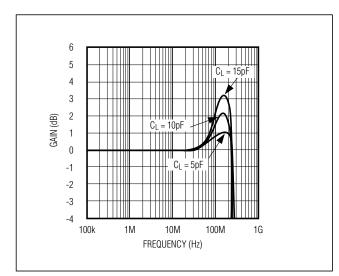


Figure 4. Small-Signal Gain vs. Frequency with Load Capacitance and No Isolation Resistor

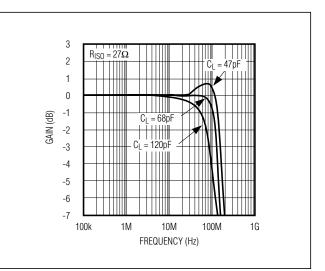
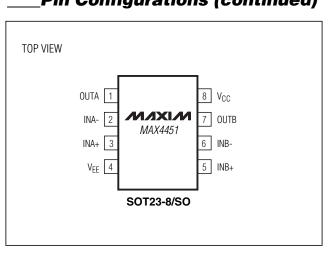


Figure 5. Small-Signal Gain vs. Frequency with Load Capacitance and  $27\Omega$  Isolation Resistor

MAX4450/MAX4451

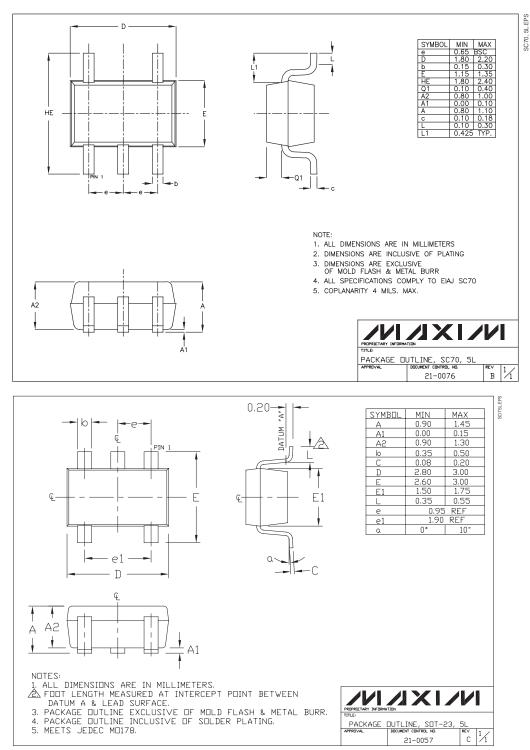


#### Pin Configurations (continued)

**Chip Information** 

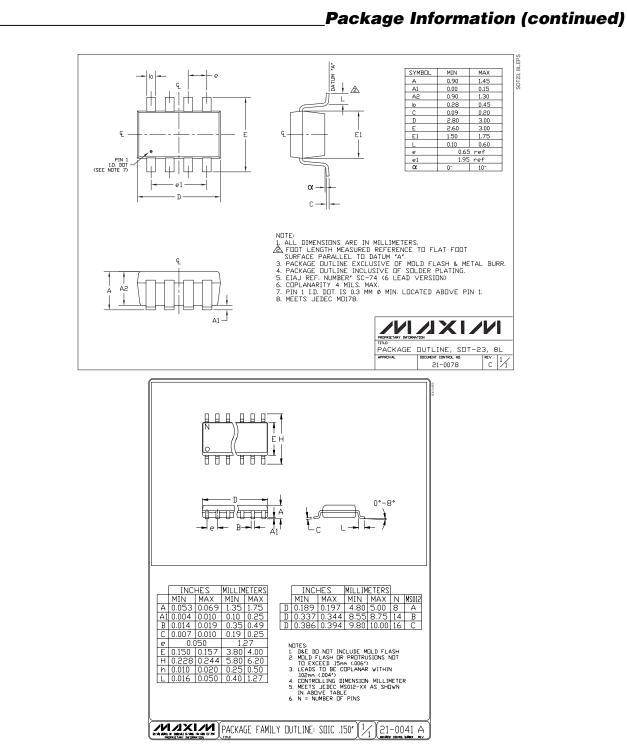
MAX4450 TRANSISTOR COUNT: 86 MAX4451 TRANSISTOR COUNT: 170

#### **Package Information**



MAX4450/MAX4451

M/IXI/M



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